

MULTI-CONTROLLER

MODEL SC-F70

MULTI-PURPOSE CONTROLLER WITH MC-COS CONTROL FEATURE

Features

Compact multi-purpose controller for a wide range of operations. Ideal for equipment automation and systems creation in many fields.

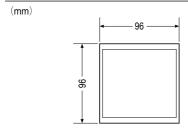
Allows pressure or temperature control when combined with automatic control valve [MC-COS (R)]. Allows PID action with auto-tuning when combined with pneumatic control valves.

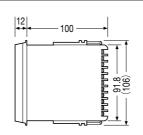
Allows dual position (ON-OFF) control when combined with ON-OFF valve.

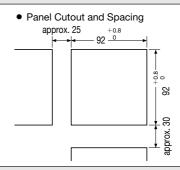
- 1. High measurement accuracy of 0.1% F.S.
- 2. Quick and easy to determine PID setting using auto-tune function for excellent stability and responsiveness. Overshoot prevention function.
- 3. Eight target settings can be stored in memory.4. Up to 4 contacts for alarm output and 3 contacts for transmission output.
- Measurement input area can accommodate various input signals.
- 6. Voltage: 100V 240V AC.
- 7. Conforms with CE marking.



Dimensions







Wiring Terminals

No.		Function
1		Ground terminal
2	100-240V AC	Power terminals
3		Power terminals
4	——ONO	
5	<u>AL2</u>	Alarm 1/Alarm 2 output terminals
6		
7	OUT1/AL3 NO	Control output 1
8	NC	or alarm output 3
9		terminals
10	0UT1/A03 + 4-20mA	Control output 1
11	4-2011A 	or transmission output 3 terminals

No.	Function					
33	R(A)					
34	R(B)					
35	T(A) \$\frac{2}{2}\tau_{1} \tau_{1} \text{SD} \tau_{2} \text{SD} \tau_{	Communications terminals				
36	T(B) T\St. 885 SS. 232C					
37	sg sg sg sg					
38	AO1 + 4-20mA	Transmission				
39		output 1 terminals				
40	OUT2/AL4	Control output 2				
41		or alarm output 4 terminals				
42	OUT2/A02 	Control output 2 or transmission				
43	4-2011A =	or transmission output 2 terminals				

No.	No.	Function					
22	12	<u>Di1</u>		Di1	Contact input		
23	13	COM(-)	9		terminals		
24	14	<u>Di2</u>	Contact input	COM(-)			
25	15	<u>Di3</u>	terminals	RSV +	Analog input		
26	16	<u>Di4</u>		0-10V、0-20mA 4-20mA	terminals		
27	17			7+	Input terminals ①Thermocouple		
28	18		-	+	input ②RTD input		
29	19	A RTD	L	0-5V 24V DC 1-5V 24V DC	③ Voltage input (LOW) ④ Voltage input		
30	20	TC + B	> IN 0-10mV 0-100mV	0-10V 0-20mA 4-20mA	(HIGH)/or Current input		
31	21	10 B 2	0-100mV 0-1V	4-5-	Output terminals Sensor power		
32							

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Specifications

ヿ				Thermocouple	RTD	DC Voltage (LOW)	DC Voltage (HIGH)	DC Current			
				•K •J	● Pt100	● 0 - 10mV	• 0 - 5V	● 0 - 20mA			
	Measurer			•E •T	● JPt100	• 0 - 100mV	●1 - 5V	• 4 - 20mA			
	Types & F	Range	s *1	•U •L	- 01 1100	• 0 - 1V	•0 - 10V	24 20117			
₹ ŀ	Effects of	f Ciana	l Decistance			♥ 0 - 1 V	♥ 0 - 10V				
-			al Resistance	approx. $0.2 \mu V/\Omega$	- 100		_	_			
Measurement Input	Input Line Resistance		_	maximum 10Ω			_				
2	•	Input Voltage				within ± 4V	within ± 12V				
	Input Impedance		1MΩ minimum		approx. 1M Ω	approx. 1MΩ	approx. 250 Ω				
	Display during Input Disconnection		Upscale	Upscale	_	_	_				
	Display during Input Short-Circuit		_	Downscale	_	_	_				
1	Measurement Accuracy		± (0.1% F.S. + 1 digit)								
Ī	Cold Junc	tion Co	mpensation Error	approx. ± 1.0 °C within range of 0 °C - 50 °C							
ľ	Sampling Period		0.25 second								
2	Set Value	s Disp	olay	4 digit 7 segment L	ED (orange)						
3	Symbol D	Display	,	3 digit 7 segment L	ED (orange)						
ا ا	Operation	<u> </u>		11 LED's indicate of	<u> </u>						
+	Setting R			Same as measurer	·						
ŀ	Setting R		· /	0.1°C [°F]	0.1°C [°F]	Donande on maseu	rement input scaling				
ŀ					0.10 [7]	Dehering on measi	iement input scailing				
	Memory /			8 memory items		0 5/ 1 5/ 0 10	N/	0 00 1 1 00			
	Analog		t Values	_	_	0 - 5V, 1 - 5V, 0 - 10	IV	0 - 20mA, 4 - 20m			
1	Setting		t Impedance			approx. 1MΩ		approx. 250 Ω			
	Input	_ '	t Accuracy	± (input span 0.19	₀ ⊦.S. +1 digit)						
╛		Inpu	t Voltage Range	within ± 12V							
-				 PID action with a 	uto-tuning						
5	Combust A	_+: T		Heating/cooling	PID action						
5	Control A	Ction i	ypes	Pressure control [MC-COS(R) / MC-VCOS(R)]							
'				Temperature control [MC-COS(R) / MC-VCOS(R)] Temperature control [MC-COS(R) / MC-VCOS(R)]							
+				Output: 4 - 20mA; Load resistance: 600 Ω maximum; Output accuracy: ± 0.1% of span							
	L La addia as		Current Output	Output: 4 - 20mA; Load resistance: 600 Ω maximum; Output accuracy: ± 0.1% of span * Selecting relay output for the heating control output sets it to transmission output 3 (AO3).							
3	Heating	,				<u> </u>	o transmission outpu	t 3 (AO3).			
5	(OUT 1) *2 Relay Outpu		Relay Output	Contact: 1c contact 250V AC, 3A (resistance load)							
Collinol Output			* Selecting current output for the heating control output sets it to alarm output 3 (AL3).								
2	Current Output		Output: 4 - 20mA; Load resistance: 600 Ω maximum; Output accuracy: ± 0.1% of span								
ξĺ	Cooling			* Selecting relay output for the cooling control output sets it to transmission output 2 (AO2).							
1	(OUT 2) *	3	Relay Output	Contact: 1a contact 250V AC, 3A (resistance load)							
┙			riolay Gatpat	* Selecting current output for the cooling control output sets it to alarm output 4 (AL4).							
			PID action with auto-tuning: When heating control output is set to current output: 4 contacts When heating control output is set to relay output: 3 contacts Heating/cooling PID action: When both heating and cooling control output are set to current output: 4 contacts When both heating and cooling control output are set to relay output: 2 contacts								
	Number	JI Alai	m Contacts		When heating control output is set to current output and cooling control output is						
- 1				set to relay output: 3 contacts							
3						Pressure control: 4 contacts Transportuse control: 4 contacts					
100			Temperature control: 4 contacts								
odibo-							deridektere " " "	L. d., d., d.			
5				No alarm, measure	ment upper limit, me	easurement lower limit	• •				
20,00	–			No alarm, measure limit, deviation upp	ment upper limit, me er & lower limits, wit	hin deviation range, m	easurement upper lin	nit with standby,			
adible Carbar	Alarm Ty	pes		No alarm, measure limit, deviation upp measurement lowe	ment upper limit, me er & lower limits, wit r limit with standby,	hin deviation range, m deviation upper limit v	easurement upper lin	nit with standby, n lower limit with			
, admin odrbar	Alarm Ty	pes		No alarm, measure limit, deviation upp measurement lowe	ment upper limit, me er & lower limits, wit r limit with standby,	hin deviation range, m	easurement upper lin	nit with standby, n lower limit with			
אימייין סמלסמי				No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure contro	ment upper limit, me er & lower limits, wit r limit with standby, upper/lower limits w ol only)	hin deviation range, m deviation upper limit v ith standby, input erro	easurement upper lin vith standby, deviatio r, FAIL status, contro	nit with standby, n lower limit with			
-	Output *	4		No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure contro Relay contact outp	ment upper limit, me er & lower limits, wit r limit with standby, upper/lower limits w ol only) ut 1a contact 250V	hin deviation range, m deviation upper limit v ith standby, input erro	easurement upper lin vith standby, deviatio r, FAIL status, contro	nit with standby, n lower limit with			
300		4		No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure contro Relay contact outp	ment upper limit, me er & lower limits, wit r limit with standby, upper/lower limits w ol only)	hin deviation range, m deviation upper limit v ith standby, input erro	easurement upper lin vith standby, deviatio r, FAIL status, contro	nit with standby, n lower limit with			
5	Output *	4		No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure contro Relay contact outp Red surface emittin	ment upper limit, me er & lower limits, wit r limit with standby, upper/lower limits w ol only) ut 1a contact 250V / g LEDs (AL1/AL2/Al	hin deviation range, m deviation upper limit w ith standby, input erro AC, 1A (resistance load 3/AL4)	easurement upper lin vith standby, deviatio r, FAIL status, contro	nit with standby, n lower limit with I error			
	Output */ Alarm Dis	4 splays	out Contacts	No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure control Relay contact outp Red surface emittin PID action with a Heating/cooling PID	ment upper limit, me er & lower limits, wit r limit with standby, upper/lower limits woll only) ut 1a contact 250V / g LEDs (AL1/AL2/Al uto-tuning: When he with action: When both he When beating set to relay ou	hin deviation range, m deviation upper limit v ith standby, input erro	easurement upper lin vith standby, deviatio r, FAIL status, contro d) set to current outpu set to relay output: 3 output are set to currer output are set to relay o	nit with standby, n lower limit with I error t: 2 contacts 3 contacts it output: 1 contact output: 3 contacts			
	Output */ Alarm Dis	4 splays	out Contacts	No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure controt Relay contact outp Red surface emittin PID action with a Heating/cooling PID Pressure control: Temperature con	ment upper limit, mer & lower limits, wit r limit with standby, upper/lower limits woll only) ut 1a contact 250V / g LEDs (AL1/AL2/Al uto-tuning: When he when both he When both he when heating set to relay ou 2 contacts trol: 2 contacts	hin deviation range, m deviation upper limit v ith standby, input erro AC, 1A (resistance load _3/AL4) sating control output is ating and cooling control ating and cooling control control output is set to co tput: 2 contacts	easurement upper lin with standby, deviation r, FAIL status, contron d) set to current output set to relay output: 3 output are set to currer output are set to relay ourrent output and cooling	nit with standby, n lower limit with I error t: 2 contacts 3 contacts It output: 1 contact output: 3 contacts g control output is			
-	Output *Alarm Dis	4 splays of Out _l	out Contacts	No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure controt Relay contact outp Red surface emittin PID action with a Heating/cooling PID Pressure control: Temperature con	ment upper limit, mer & lower limits, wit r limit with standby, upper/lower limits woll only) ut 1a contact 250V / g LEDs (AL1/AL2/Al uto-tuning: When he when both he When both he when heating set to relay ou 2 contacts trol: 2 contacts	hin deviation range, m deviation upper limit v ith standby, input erro AC, 1A (resistance load _3/AL4) sating control output is ating and cooling control ating and cooling control control output is set to co tput: 2 contacts	easurement upper lin with standby, deviation r, FAIL status, contron d) set to current output set to relay output: 3 output are set to currer output are set to relay ourrent output and cooling	nit with standby, n lower limit with I error t: 2 contacts 3 contacts It output: 1 contact output: 3 contacts g control output is			
-	Output */ Alarm Dis	4 splays of Out _l	out Contacts	No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure controt Relay contact outp Red surface emittin PID action with a Pressure control: Pressure control: Temperature con Measured values, s	ment upper limit, mer & lower limits, wit r limit with standby, upper/lower limits woll only) It 1a contact 250V / g LEDs (AL1/AL2/Aluto-tuning: When he with action: When both he when both he when heating set to relay ou 2 contacts trol: 2 contacts et values, deviation	hin deviation range, m deviation upper limit v ith standby, input erro AC, 1A (resistance load _3/AL4) rating control output is rating and cooling control ating and cooling control control output is set to co tput: 2 contacts	easurement upper lin with standby, deviation r, FAIL status, contron d) set to current output set to relay output: 3 output are set to currer output are set to relay ourrent output and cooling	nit with standby, n lower limit with I error t: 2 contacts 3 contacts It output: 1 contact output: 3 contacts g control output is			
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-	Output *Alarm Dis	4 splays of Outp		No alarm, measure limit, deviation upp measurement lowe standby, deviation (for pressure controt Relay contact outp Red surface emittin PID action with a Pressure control: Pressure control: Temperature con Measured values, s	ment upper limit, mer & lower limits, wit r limit with standby, upper/lower limits woll only) It 1a contact 250V / g LEDs (AL1/AL2/Aluto-tuning: When he with action: When both he when both he when heating set to relay ou 2 contacts trol: 2 contacts et values, deviation	hin deviation range, m deviation upper limit v ith standby, input erro AC, 1A (resistance load _3/AL4) rating control output is rating and cooling control ating and cooling control control output is set to co tput: 2 contacts	easurement upper lin with standby, deviation r, FAIL status, contron d) set to current output set to relay output: 3 output are set to currer output are set to relay ourrent output and cooling	nit with standby, n lower limit with I error t: 2 contacts 3 contacts it output: 1 contact output: 3 contacts g control output is			



¹ Values changeable with jumper switches and PARAMETERS.
2 Either current output or relay contact output can be specified for heating control output (but set to current output for pressure control or temperature control).
3 Either current output or relay contact output can be specified for cooling control output: cooling control output only set for heating/cooling PID action.
4 Specifications shown are for Alarms 1 and 2. Alarm 3 is for heating control output; Alarm 4 is for cooling control output.



Specifications

ont	Analog Setting Input Types	No. of Contacts	1 analog input contact and 1 no-voltage contact			
트		Function	Analog input-enters target setting from outside			
og		Turiction	Contact input-MAN/AUT or LOC/REM selection			
External Remote Input	Area Selection	No. of Contacts	4 no-voltage contacts			
a E	Contact		Contact input-MAN/AUT selection and area selection,			
ter	Input Types	Function	or LOC/REM selection and area selection,			
	mpat Typoo		or Area selection			
Communi- cations	Communication	ns Method	RS-422A: 4-wire type; RS-485: 2-wire type; RS-232C			
Comr	Communication	ns Code	JIS (ASCII) 7-bit code			
stic	Check Items		ROM/RAM check, input value check, CPU power monitoring, watchdog timer			
Self-Diagnostic Function	Error Displays		FAIL lamp lights up (except during input error)			
Funda	Error Output		When FAIL lamp lights up: all output OFF			
Sel	Error Output		During input error: action selectable			
	Ambient Tempe	erature	0 °C - 50 °C			
ition	Ambient Humidity		20 - 85% RH			
Ambient Sonditions	Line Voltage Fluctuations		Rated voltage ± 10%			
	Power Frequency Fluctuations		Rated value ± 5%			
	Insulation Resistance		Between measurement terminal and ground: 500V DC/20M Ω minimum			
ဍ			Between power terminal and ground: 500V DC/20MΩ minimum			
뎙	Maximum Allow	und Valtaga	Between measurement terminal and ground: 1000V AC for 1 minute			
<u> i</u>	Maximum Allowed Voltage		Between power terminal and ground: 1500V AC for 1 minute			
9Ċ.	Line Voltage		100 - 240V AC, 50/60Hz			
Specifications	Power Consum	ption	13VA at 240V • 10VA at 100V			
	Effect of Power	Outage	No effect for power outage of 50 msec or less			
General	Memory Backu	р	Setting data backed up by lithium battery. Service life approximately 10 years *			
g	Weight	·	Approximately 600 g maximum			
	Accessories		1 set of fittings (2)			

^{*} Will depend on product storage time, storage environment, operating conditions, etc.

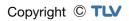


To avoid abnormal operation, accidents or serious injury, DO NOT use this product outside of the specification range. Local regulations may restrict the use of this product to below the conditions quoted.

Measurement Input Types & Ranges

	Input Type	Input Range [°C]	Code	Input Range [°F]	Code	
	Type K (EX-: CA)	0.0 - 400.0	0	0.0 - 800.0	200	
	[JIS/IEC]	0.0 - 800.0	1	0.0 - 800.0	200	
(DE)	Type J (EX-: IC)	0.0 - 400.0	10	0.0 - 700.0	210	
	[JIS/IEC]	0.0 - 800.0	11	0.0 - 700.0	210	
Thermocouple	Type E (EX-: CRC)	0.0 - 700.0	20	0.0 - 999.9	220	
8	[JIS/IEC]	0.0 - 700.0	20	0.0 - 999.9	220	
Ĕ	Type T (EX-: CC)	0.0 - 400.0	30	0.0 - 700.0	230	
욛	[JIS/IEC]	0.0 - 400.0	30	0.0 - 700.0	230	
	Type U [DIN]	0.0 - 600.0	40	0.0 - 999.0	240	
	Type L [DIN]	0.0 - 400.0	50	0.0 - 700.0	250	
	JPt 100 [JIS]	0.0 - 300.0	400	0.0 - 600.0	500	
E G	JP1 100 [JIS]	0.0 - 500.0	401	0.0 - 900.0	501	
ᇤ	Pt 100 [JIS/IEC]	○ 0.0 - 300.0	410	0.0 - 600.0	510	
	Pt 100 [JIS/IEC]	0.0 - 600.0	411	0.0 - 999.9	511	
ω_	0 - 10mV		600			
Voltage (LOW)	0 - 100mV	Arbitrary scaling possible	601			
۶۳	0 - 1V		602			
0.0	0 - 5V		610			
Voltage (HIGH)	1 - 5V	Arbitrary scaling possible	611			
	0 - 10V		612			
eut	0 - 20mA	Aubituan caalina naasibla	700	1		
Current	● 4 - 20mA	Arbitrary scaling possible	701			

Factory default for pressure control
 Factory default for all control types other than pressure control





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Specifications Checksheet

_		Remarks				
Model		For boxes in the "code" section at left, enter the appropriate code from among the specification items below each box.				
Basic Specifications	Control Operation Type	PID action with auto-tuning Heating / cooling PID action Pressure control operation [MC-COS (R)-3] Pressure control operation [MC-COS (R)-16, 15-50mm] Pressure control operation [MC-COS (R)-16, 65-150mm] Pressure control operation [MC-COS-21] Pressure control operation [MC-VCOS (R)] Temperature control operation [MC-COS (R)-16] Temperature control operation [MC-VCOS (R)]	0 1 2 3 4 5 6 7 8			Select to match the valve that will be used with the controller.
Additional Specifications	Remote External Input	 None Area selection input (Di 4 contacts) Analog setting input (RSV + Di 1 contact) 		Remote area selection operation is possible when "D" is specified. Remote analog setting operation is possible when "A" is specified.		
Additional S	Communications Function	 None RS-232C RS-422A (4-wire type) RS-485 (2-wire type) 	Select to match the computer to be connected.			
*	Measurement Input Types & Ranges	☐ RTD ☐ Thermocouple (TC) ☐ Voltage (low) input ☐ Voltage (high) input ☐ Current input	-Select the type and range code from "Table of Measurement Input Types and Ranges". -Values can be changed after the controller has been shipped by changing jumper switches and PARAMETERS.			
Initial Settings*	Types of Remote Analog Setting Input	Current input	Specify only for models equipped with remote analog setting input.			
Init	Pressure Sensor Range	□ 0 - 2000 kPaG □ 0.00 - 20 □ 0 - 1000 kPaG □ 0.00 - 10 □ 0 - 500 kPaG □ 0.00 - 5 □ -101.3 - 298.7 kPaG □ -760 - 23 □ 0 - 400 kPa abs □ 0.0 - 30 □ 0.00 - 20.00 barg □ 0.0 - 14 □ 0.00 - 10.00 barg □ 0.0 - 14 □ 0.00 - 5.00 barg □ 0.0 - 7 □ -1013 - 2987 mbarg □ -14.70 - 43 □ 0 - 4000 mbar abs □ 0.00 - 58 □ Other: range(-) unit ()	Specify the range of the pressure sensor to be connected (when pressure control has been selected).			

^{*} Initial settings can be changed after the controller has been shipped from the factory. When not specified in advance, items are set to their default values before shipment

Manufacturer

TLV® CO.,LTD.

Kakogawa, Japan
is approved by LRQA Ltd. to ISO 9001/14001

ISO 9001/ISO 14001



