

liahts

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# **5. OPERATING PRECAUTIONS**

Read and understand the following precautions before starting operation

#### CAUTIONS

- There is no power switch on this instrument, so the instrument starts operation
- immediately following initial power ON (Factory set value: RUN). • If the input signal wiring is disconnected or short-circuited (RTD input only), the instrument determines that input error (burnout, etc.) has occurred.
- <Burnout direction>

Thermocouple input\*: Upscale or Downscale

- Upscale (when input break), Downscale (when short-circuited) RTD input: Voltage input, current input
- Downscale or Indicate the value near 0 \* Burnout direction can be selected by Engineering mode. (Factory set value: Upscale) <Output at burnout>

Control output: According to the contents set by Control output at burnout (Factory set value: 0 [Result of control computation])

Event output: According to the contents set by Event output action at input burnout (Factory set value: 0 [The Event output is not forcibly turned ON when the Burnout function is activated.])

 A power failure of 20 ms<sup>\*1</sup> or less will not affect the control action. When a power failure of more than 20 ms<sup>\*1</sup> occurs the instrument assumes that the power has been turned off. When power returns the controller will retain the conditions that existed prior to shut down\*

- <sup>1</sup> 10 ms in case of 24 V AC/DC power supply
- \*2 In case of AUTO mode: Output changes from the Output limiter low with control calculation results.
- In case of a Manual (MAN) m

Output status is defined as follows by the Bumpless mode setting in the Engineering mode. In case of "0: without bumpless" In case of "1: with bumpless Preset manual value is output. PID control: Output limiter low is output Heat/Cool PID control: Output is 0 %

- The Event hold action is activated when the power is turned on or when transferred from STOP mode to RUN mode. (Event type with hold action)
- The Event re-hold action is activated when not only the SV is changed, but also when power is turned on or when transferred from STOP mode to RUN mode. (Event type with re-hold action)

# **6. FUNCTIONS RELATED TO OPERATION**

Refer to • Set value change and registration for basic data setting in this manual Functions related to operation are explained below

#### 6.1 RUN/STOP Transfer

It is possible to transfer between control start (RUN) and control stop (STOP). RUN/STOP transfer can be performed by key operation, or by using the "RUN/STOP setting" in Engineering mode. These two methods are linked together. For example, if the keys are used to transfer from RUN to STOP, the setting of "RUN/STOP setting" in Engineering mode will also change to "STOP.

#### State of this instrument when set to STOP mode

STOP display	STOP lamp lights (Green). Displays the STOP symbol "STOP" on the SV or PV displays. [Factory shipment: SV display + STOP lamp]		
Control output	When the time-proportional control output: Output OFF When the continuous control output: Output of -5 %		
Event output	Output depending on the "Output action at STOP mode" [Factory shipment: Output OFF (Contact open)]		
Autotuning (AT)	AT canceled (The PID constants are not updated)		
Parameters	The Set value (SV) and Parameter setting mode can be set, and mode switching can be operated.		

#### State of this instrument when set to RUN mode

If the instrument is transferred to RUN mode from STOP mode, it performs the same operation (control RUN, event determination start-up) as the power-on.

#### RUN/STOP transfer by front key operation

<BLIN mode (factory shipment)> "STOP" character in the STOP mode;

incore mode (nactory emprisency					
	Character	STOP lamp	Key operation or communication <sup>1</sup>	Digital input (DI) <sup>1,3</sup>	Timer function <sup>2</sup>
	ĽSFP	Lighting	STOP	RUN	
<stop mode=""></stop>	dSFP	Lighting	RUN	STOP	
(2 seconds or more)	SroP	Lighting	STOP	STOP	
	<i>L 2L 4</i>	Flashing	RUN	RUN	STOP
STOP lamp lights	$^1$ Communication, Digital input (DI): Optional function $^2$ Factory shipment: Timer function is unused $^3$ When no Digital input (DI) is supplied: Only $5\Gamma_0P$ or $\Gamma_5\Gamma_P$ is displayed.				

## Performing RUN/STOP transfer in the "RUN/STOP setting"

• To change from RUN mode to STOP mode



## • To change from STOP mode to RUN mode

1. Follow the steps above to display the RUN/STOP setting screen



## 6.2 Autotuning (AT) Start/Stop

The AT function automatically measures, computes and sets the optimum PID values.

#### Caution for using the Autotuning (AT)

- When a temperature change (UP and/or Down) is 1 °C or less per minute during AT, AT may not be finished normally. In that case, adjust the PID values manually. Manual setting of PID values may also be necessary if the set value is around the ambient temperature or is close to the maximum temperature achieved by the load.
- If the manipulated output value may be limited by the output limiter setting, the optimum PID values may not be calculated by AT

### Requirements for Autotuning (AT) start

Start the AT when all following conditions are satisfied:			
Operation state	PID control		
	RUN		
Parameter setting	Output limiter high $\geq$ 0.1 %, Output limiter low $\leq$ 99.9 %		
	[Heat/Cool control type: Output limiter high (heat-side) ≥ 0.1 %, Output limiter high ccool-side) ≥ 0.1 %		
Input value state	The Measured value (PV) is not underscale or overscale.		

### Requirements for Autotuning (AT) cancellation

If the AT is canceled according to any of the following conditions, the controller immediate changes to PID control. The PID values will be the same as before AT was activated.

Operation state	When the PID/AT transfer is changed to the PID control.		
	When the RUN/STOP mode is changed to the STOP mode.		
	When the Auto/Manual mode is changed to the Manual mode.		
Parameter changing	When the Set value (SV) is changed.		
	When the PV bias or the PV digital filter is changed.		
	When the Output limiter value is changed.		
Input value state	When the Measured value (PV) goes to underscale or overscale.		
AT execution time	When the AT does not end in 9 hours after AT started.		
Power failure	When the power failure of more than 20 ms occurs.		
	(10 ms or more with 24V AC/DC power supply.)		
Instrument error	When the instrument is in the FAIL state.		

#### Autotuning (AT) Start/Stop operation

The Autotuning function can start from any state after power on, during a rise in temperature or in stable control.

If AT ends normally, the LBA time is automatically set twice as large as the Integral time.

#### 6.3 Startup Tuning (ST)

Startup tuning (ST) is a function which automatically computes and sets the PID values (Proportional band: heat-side only) from the response characteristics of the controlled system at power ON, transfer from STOP to RUN, and Set value (SV) change. As simple autotuning, the PID values can be found in a short time without disturbing controllability for controlled systems with slow response at power ON.

#### Caution for using the Startup tuning (ST)

- For ST at power ON or transfer from STOP to RUN, always set the heater power to ON simultaneously with the start of tuning or before the start of tuning
- Start ST in the state in which the temperature differential of the Measured value (PV) and Set value (SV) at the start of ST is twice the proportional band, or greater
- When the manipulated output value may be limited by the output limiter setting, the optimum PID values may not be calculated by ST.

#### Requirements for Startup tuning (ST) start

Start the ST when all following conditions are satisfied

On enertient state	PID control
Operation state	RUN
Parameter setting	ST is set to ON. (Execute once, Execute always)
	Output limiter high $\geq$ 0.1 %, Output limiter low $\leq$ 99.9 %
	[Heat/Cool control type: Output limiter high (heat-side) $\geq 0.1 \%$ ]
Input value state	The Measured value (PV) is not underscale or overscale.
	At ST at setting change, the Measured value (PV) shall be stabilized.
	Set value (SV) > Measured value (PV) [Heat/Cool PID control]
Output value state	At startup, output is changed and saturated at the Output limiter
	high or the Output limiter low [Heat/Cool control type: Output limiter
	high (heat-side)].

#### Requirements for Startup tuning (ST) cancellation

If the ST is canceled according to any of the following conditions, the controller immediately changes to PID control. The PID values will be the same as before ST was activated.

	When the AT is activated.		
Operation state	When the RUN/STOP mode is changed to the STOP mode.		
	When the Auto/Manual mode is changed to the Manual mode.		
	When ST is set to "0 (ST unused)."		
Parameter changing	When the PV bias or the PV digital filter is changed.		
	When the Output limiter value is changed.		
Input value state	When the Measured value (PV) goes to underscale or overscale.		
ST execution time	When the ST does not end in hundred minutes after ST started		
Power failure	When the power failure of more than 20 ms occurs. (10 ms or more with 24V AC/DC power supply.)		
Instrument error	When the instrument is in the FAIL state.		

#### Startup tuning (ST) setting

Setting example: When executing ST only 1 time at power ON

#### 1. Check the start condition

- Function block F52 of Engineering mode.

#### 2. Set the execution method



- When ST was interrupted, the setting does not change to "0: ST unused." ST starts

The Fine tuning function allows you to change the response of the set PID constant control. The control response can be made "faster" or "slower" by simply changing the Fine tuning setting (6 levels: -3 to +3) in Parameter setting mode; the PID constant can be kept unchanged.



#### Fine tuning setting

Setting example: To slow the response (when "-1" is set)



Ш If the set value of Fine tuning is returned to "0: Unused," Fine tuning correction will no longer be applied to control.

#### 6.5 Interlock Release

The Event interlock action holds the event state even if the Measured value (PV) is out of the event zone after it enters the event zone once. The Interlock release can be made by the key operation

To validate the Interlock function, it is necessary to set Event interlock (EIL) to 1: Used" in Engineering mode. (Factory shipment: Interlock function OFF)

## Refer to Parameter List.



value (PV) [Flashing]	PV is outside of input range.	Prior to replacing the sen always turn the power OF
0000	Over-scale: PV is above the display range	RUN/STOP transfer.
[Flashing]	limit high	Check input range, sensor and
UUUU	Underscale:	sensor connection.
[Flashing]	limit low	

#### Self-diagnostic error

wo or more errors occur simultaneously, the total summation of these error codes is displayed.				
Description	Action	Operation at error	Solution	
Err / Flashing Adjustment data error Err / Flashing Data back-up error Err / Flashing VD conversion error *	Indication lamp: All lamp turns off	Control output: Time-proportional control output: OFF Continuous control output: Output of -5 % Transmission output: Output of -5 % FAIL output: Contact open	Turn off the power at once. If an error occurs after the power is turned on again, please contact RKC sales office or the agent.	
ower supply voltage abnormal	All display is OFF	[When FAIL is selected for the event (EV)]		
/atchdog timer				

\* Including temperature compensation error

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